

## 4 - PIN TABLES FOR SA060

### 4.1 - J1 Controller setting

Connector type: Micro USB AB type

This port is a USB 2.0 communication port at 12 Mbps, for set, tuning and diagnostic procedures via software and for firmware upgrade. It's allowed to use USB 2.0 HUBs in cascaded connection to visualize more axes with the same PC.



Before connecting a desktop PC to the controller, ensure that PC Power Earth is the same of the controller, otherwise, use an insulated laptop PC.

### 4.2 - J2 Fieldbus connection

Connector type: double RJ45: IN (A) and OUT (B) port

The ports configuration differs according to the chosen fieldbus type (control mode CM, EC or PN). Please refer to the Start-up manual of SA060 controller.

### 4.3 - J3 I/O signals and power supply

Connector type: double row, pitch 3.5 mm

Use at least 0.5 mm<sup>2</sup> section cables (AWG20) for pin 11 and pin 20. A shielded cable is required for pins from 12 to 15.

Pin	Tag	Description
1	REF-	±10 V 12 bit ADC differential analog input for main reference. Available also as digital input IN_6 (single ended PNP).
2	REF+	
3	GND	0 ÷ 10 V 12 bit ADC single-ended analog input for auxiliary reference. Available also as PNP digital input IN_7.
4	RIF AUX	
5	IN_0	Programmable digital input function defined by chosen operating mode
6	IN_1	
7	IN_2	
8	IN_3	
9	IN_4	
10	IN_5	
11	GND	0V - Ground reference for +24 V DC supply and for digital input signals IN_0 to IN_5.
12	DIR+	Frequency main reference input
13	DIR-	
14	PULSE+	
15	PULSE-	
16	OUT OK+	Optoinsulated programmable NPN/PNP digital output. Normally used for "Drive OK" function. HIGH: active, no alarms occurred. LOW: disabled; an error occurs and the controller shuts down in fault condition.
17	OUT OK-	
18	OUT1+	Optoinsulated programmable NPN/PNP digital output.
19	OUT1-	
20	+ 24V	+24 V DC - Backup logic supply when main supply is disconnected.

#### 4.4 - J4 Motor feedback

Connector type: double row, pitch 3.5 mm

Use shielded cable and connect shield to PE. Keep I/O cables far from supply and feedback cables.

Pin	Tag	Description
1	A+	Differential line driver (5V) input for incremental channel A.
2	A-	
		A
3	B+	Differential line driver (5V) input for incremental channel B.
4	B-	
		B
5	Z+ / CK+	Differential line driver (5V) input for channel Z of incremental encoder.
6	Z- / CK-	Differential line driver (5V) output for CLOCK data for SSI absolute encoder
	Z	Single (5V) Open Collector and Push Pull input for incremental channel Z.
7	+5E	+5V encoder supply and for pull up resistors.
8	GND	Common Ground for encoder supply and signals.
9	D-	Differential line driver (5V) input for DATA for SSI absolute encoder.
10	(HA) / D+	
		HA / D+
11	HB	HALL sensor B signal
12	HC	HALL sensor C signal

#### 4.5 - J5 Motor connection and power supply

Connector type: Power connector, pitch 5 mm

Before providing power supply voltage, ensure that J5 connector is properly inserted.

Connect correctly U,V,W wiring both the controller and the motor: the inversion of the phases do not invert the rotation direction of the motor.

Pin	Tag	Description
1	+DC	DC power supply connection. Ensure that -DC pin, power cable shields and encoder cable shield are connected to PE
2	-DC	
3	U	U motor connection
4	V	V motor connection
5	W	W motor connection

#### 4.6 - J6 Incremental encoder repetition

connector type: Push-in, pitch 2.5 mm

This is a 5V hardware buffered line - controller output for incremental channel and zero index derived from main feedback incremental encoder.

Pin	Tag	Description
1	SHIELD	Cable shield connection
2	GND	Common ground
3	Z+	Differential line controller (5V) output for incremental channel Z
4	Z-	
5	B+	Differential line controller (5V) output for incremental channel B
6	B-	
7	A+	Differential line controller (5V) output for incremental channel A
8	A-	

## 5 - PIN TABLES FOR SA230

### 5.1 - J1 Logic supply and SPD function

connector type: single row, pitch 5 mm

Pin	Tag	Description
1	+24 V IN	DC power supply connection for logic
2	GND IN	
3	SPD IN 1	Input of redundant channel 1 for SPD safety function
4	+24V SPD	Power supply output for the SPD safety circuit.
5	SPD IN 2	Input of redundant channel 2 for SPD safety function

This port provide connections for logic supply and for the security function SPD (secure power disable). This function is also called STO.

### 5.2 - J2 Controller setting

Connector type: Micro USB AB type

Please refer to point 5.1

### 5.3 - J3 Fieldbus connection

Connector type: double RJ45: IN (A) and OUT (B) port.

The ports configuration differs according to the chosen fieldbus type (control mode CM, EC or PN). Please refer to the Start-up manual of SA230 controller.

### 5.4 - J4 I/O signals

connector type: double row, pitch 3.5 mm

A shielded cable is required for pins from 11 to 14.

Pin	Tag	Description
1	IN_C	Common reference for NPN or PNP digital inputs.
2	IN_0	NPN/PNP digital input with function defined by chosen operating mode
3	IN_1	
4	IN_2	
5	IN_3	
6	IN_4	
7	IN_5	
8	GND	0V - Ground reference for analogue input
9	REF+	±10 V 12 bit ADC differential analog input for main reference Available also as digital input IN_6 (single ended PNP)
10	REF-	
11	CCW/DIR/CH +	Frequency main reference input
12	CCW/DIR/CH -	
13	CW/PULSE/CH +	
14	CW/PULSE/CH -	
15	OUT 0 +	Optoinsulated programmable NPN/PNP digital output. Normally used for "Drive OK" function HIGH: active, no alarms occurred LOW: disabled; an error occures and the controller shuts down in fault condition
16	OUT 0 -	
17	OUT1 +	Optoinsulated programmable NPN/PNP digital output
18	OUT1 -	
19	(OUT2+) / REF AUX	0 ÷ 10 V 12 bit ADC single-ended analog input for auxiliary reference (GND at pin 8) Available also as PNP digital input IN_7
	OUT2 + / (REF AUX)	Optoinsulated programmable NPN/PNP digital output
20	OUT2 -	

### 5.5 - J5 Motor feedback

Connector type: double row, pitch 3.5 mm

Use not twisted shielded cable for incremental and absolute encoder feedback. Use twisted shielded cable for resolver feedback. Keep I/O cables far from supply and feedback cables.

Pin	Tag	Description
1	A + / SIN+	Differential line controller (5V) input for incremental channel A. Differential input for Resolver channel SIN.
2	A - / SIN -	
		A
3	B + / COS+	Differential line driver (5V) input for incremental channel B. Differential input for Resolver channel COS.
4	B - / COS -	
		B
5	Z + / CK+ / EXC+	Differential line controller (5V) input for channel Z of incremental encoder. Differential line controller (5V) output for CLOCK data for SSI absolute encoder Differential output for reference to Resolver feedback.
6	Z - / CK - / EXC	
7	PTC+	Digital input for motor PTC. If motor is devoid of PTC, ensure to short pin 7 and 8.
8	PTC-	
9	+5E	+5V encoder supply.
10	GND	Common Ground for encoder supply and signals.
11	D-	Differential line controller (5V) input for DATA for SSI absolute encoder.
12	(HA) / D +	
		HA / D +
13	HB	HALL sensor B signal
14	HC	HALL sensor C signal
15	SHIELD	Feedback and signal cable shield. This pin is connected to controller Power Earth (PE)
16	SHIELD	

### 5.6 - J6 Motor power supply

Connector type: power connector, pitch 5 mm

Before providing power supply voltage, ensure that J5 connector is properly inserted. Connect correctly U,V,W wiring both the controller and the motor: the inversion of the phases do not invert the rotation direction of the motor.

Pin	Tag	Description
1	U	U motor connection
2	V	V motor connection
3	W	W motor connection
4	PE	Power Earth connection , PE

### 5.7 - J7 Controller logic supply and braking

Connector type: single row, pitch 5 mm

If DC power supply or DC linked configuration is used, it's recommended to use shielded cable; please connect shields to earth both side of connection.

Pin	Tag	Description
1	- DC BUS	Connection for DC power supply
2	+ DC BUS	
3	EXT BRK	External braking resistor connection
4	L1	Connection for AC power supply: • L1 - L2 for single phase controller version • L1 - L2 - L3 for triphase controller version
5	L2	
6	L3	
7	PE	Controller power supply, Power Earth

### 5.8 - J8 Incremental encoder repetition

Connector type: Push-in, pitch 2.5 mm

This is a 5V hardware buffered Line-Driver output for incremental channel and zero index derived from main feedback incremental encoder. Please refer to point 5.7: pin table is the same.